

Assignment: HW7 [40 points]

Assigned: 2006/11/15

Due: 2006/11/22

Solutions

P7.1 [6 + 8 = 14 points]

A particle of mass m can move in one dimension under the influence of two springs connected to two walls that are a distance a apart, as shown in Fig. 7.1. The springs obey Hooke's law, have zero unstretched lengths and spring constants k_1 and k_2 respectively.

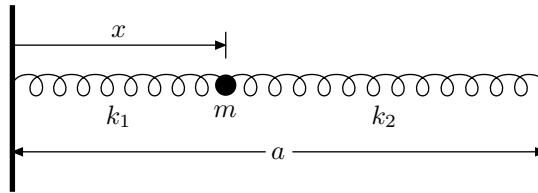


Figure 7.1

- (a) Let x be the length of the first spring, and b its equilibrium value. Using the displacement from the equilibrium, $q = x - b$, as the generalized coordinate, find the Hamiltonian and the total energy of the system, and examine if these quantities are conserved.
- (b) Now consider the coordinate transformation

$$Q = q - b \sin(\omega t), \quad (1)$$

where ω is some constant (not necessarily the natural frequency of the system). Find the Hamiltonian and the total energy of the system in terms of Q and its conjugate momentum P , and examine if these quantities are conserved.

- S7.1** (a) The equilibrium condition requires the forces exerted on the mass by the two springs to cancel each other:

$$k_1 b = k_2(a - b), \quad \text{or,} \quad b = \frac{k_2}{k_1 + k_2} a. \quad (2)$$

Thus, the potential energy of the particle is

$$\begin{aligned} V &= \frac{1}{2}(k_1 x^2 + k_2(a - x)^2) \\ &= \frac{1}{2}(k_1(q + b)^2 + k_2(a - q - b)^2) \\ &= \frac{1}{2}(kq^2 + \frac{k_1 k_2}{k} a^2), \end{aligned} \quad (3)$$

where $k = k_1 + k_2$, and the kinetic energy is

$$T = m\dot{q}^2 \quad (4)$$

We can drop the constant term $\frac{k_1 k_2}{k} a^2$ from the potential energy and write the Lagrangian as

$$L(q, \dot{q}) = \frac{1}{2} m \dot{q}^2 - \frac{1}{2} k q^2, \quad (5)$$

and the total energy as

$$E = \frac{1}{2} m \dot{q}^2 + \frac{1}{2} k q^2. \quad (6)$$

The momentum corresponding to q is

$$p = \frac{\partial L}{\partial \dot{q}} = m \dot{q} \quad (7)$$

or, $\dot{q} = \frac{p}{m},$

which gives the Hamiltonian

$$H(q, p) = p \dot{q} - L = \frac{p^2}{2m} + \frac{kq^2}{2}. \quad (8)$$

Neither the Lagrangian nor the Hamiltonian has any explicit time dependence. Therefore, both the total energy and the Hamiltonian are conserved.

(b) Under the transformation,

$$q = Q + b \sin(\omega t) \quad (9)$$

and

$$\dot{q} = \dot{Q} + b\omega \cos(\omega t). \quad (10)$$

Therefore, from Eq. 5,

$$L(Q, \dot{Q}) = \frac{m}{2} (\dot{Q} + b\omega \cos(\omega t))^2 - \frac{k}{2} (Q + b \sin(\omega t))^2, \quad (11)$$

and

$$E = \frac{m}{2} (\dot{Q} + b\omega \cos(\omega t))^2 + \frac{k}{2} (Q + b \sin(\omega t))^2, \quad (12)$$

Thus,

$$P = \frac{\partial L}{\partial \dot{Q}} = m(\dot{Q} + b\omega \cos(\omega t)) \quad (13)$$

$$\text{or, } \dot{Q} = \frac{P}{m} - b\omega \cos(\omega t),$$

Therefore,

$$E = \frac{P^2}{2m} + \frac{k}{2} (Q + b \sin(\omega t))^2, \quad (14)$$

and

$$\begin{aligned} H(Q, P) &= P \dot{Q} - L \\ &= P \left(\frac{P}{m} - b\omega \cos(\omega t) \right) - \frac{P^2}{2m} + \frac{k}{2} (Q + b \sin(\omega t))^2 \\ &= \frac{P^2}{2m} + \frac{k}{2} (Q + b \sin(\omega t))^2 - b\omega P \cos(\omega t) \\ &= E - b\omega P \cos(\omega t). \end{aligned} \quad (15)$$

Now,

$$\frac{dE}{dt} = \frac{P\dot{P}}{m} + k(Q + b \sin(\omega t))(\dot{Q} + b\omega \cos(\omega t)) = \frac{P}{m}(\dot{P} + k(Q + b \sin(\omega t))), \quad (16)$$

but,

$$\dot{P} = -\frac{\partial H}{\partial Q} = -k(Q + b \sin(\omega t)). \quad (17)$$

So, the RHS of Eq. 16 vanishes, i.e.,

$$\frac{dE}{dt} = 0. \quad (18)$$

So, the energy is conserved, as expected. However, the new Hamiltonian depends explicitly on t , and is therefore not conserved.

P7.2 [4 + 2 = 6 points]

Let (q, p) be the phase-space coordinates of a system with one degree of freedom.

(a) Under what conditions is the transformation

$$Q = \alpha \frac{p}{q}; \quad P = \beta q^2 \quad (19)$$

canonical (α and β are constants)?

(b) Find a suitable generating function of type 1, $F_1(q, Q)$, for the above transformation.

S7.2 (a) First, let us find the inverse transformations $q(Q, P)$ and $p(Q, P)$:

$$q = \sqrt{\frac{P}{\beta}}; \quad p = \frac{qQ}{\alpha} = \frac{Q}{\alpha} \sqrt{\frac{P}{\beta}}. \quad (20)$$

Now use the conditions that yield non-zero partial derivatives:

$$\begin{aligned} \left(\frac{\partial P}{\partial q} \right)_p &= - \left(\frac{\partial p}{\partial Q} \right)_P \\ \Rightarrow 2\beta q &= -\frac{1}{\alpha} \sqrt{\frac{P}{\beta}} = -\frac{q}{\alpha}. \end{aligned} \quad (21)$$

Therefore, the transformation is canonical if

$$2\alpha\beta = -1. \quad (22)$$

(b) If $F_1(q, Q)$ is a generating function, then

$$p = \left(\frac{\partial F_1}{\partial q} \right)_Q \quad (23)$$

Thus using Eq. 20 and the condition 22,

$$F_1(q, Q) = \frac{q^2 Q}{2\alpha} = -\beta q^2 Q. \quad (24)$$

Note that the generating function is not unique.

P7.3 [6 points]

Consider the (continuous and regular) one-parameter group of canonical transformations ψ_θ defined as the solution to the differential equation

$$\frac{\partial \psi^\mu(\omega_0; \theta)}{\partial \theta} = \epsilon^{\mu\nu} \left[\frac{\partial \phi(\omega)}{\partial \omega^\nu} \right]_{\omega^\mu = \psi^\mu(\omega_0; \theta)} = \epsilon^{\mu\nu} \frac{\partial \phi(\omega_0; \theta)}{\partial \psi^\nu}, \quad (25)$$

where ϕ^μ are some functions of ω , independent of θ . Indeed, ϕ^μ is the inverse of the ratio of the infinitesimal change in the parameter θ and the corresponding change in the phase space coordinate ω^μ :

$$\omega'^\mu = \omega^\mu + \delta\theta \phi^\mu(\omega). \quad (26)$$

Show that a function $A(\omega) = A(\psi(\omega_0; \theta)) = A_\theta(\omega_0)$ will obey the differential equation

$$\frac{\partial A_\theta(\omega_0)}{\partial \theta} = \{A_\theta(\omega_0), \phi(\omega_0)\}_{\omega_0}, \quad (27)$$

which then leads to the power series solution

$$A(\omega) = A_\theta(\omega_0) = A(\omega_0) + \theta \{A_\theta(\omega_0), \phi(\omega_0)\} + \frac{\theta^2}{2!} \{\{A_\theta(\omega_0), \phi(\omega_0)\}, \phi(\omega_0)\} + \dots \quad (28)$$

S7.3

$$\begin{aligned} \frac{\partial A_\theta(\omega_0)}{\partial \theta} &= \frac{\partial A(\psi(\omega_0; \theta))}{\partial \theta} \\ &= \frac{\partial A(\psi)}{\partial \psi^\lambda} \frac{\partial \psi^\lambda}{\partial \theta} \\ &= \epsilon^{\lambda\mu} \frac{\partial A(\psi)}{\partial \psi^\lambda} \frac{\partial \phi(\psi)}{\partial \psi^\mu} \\ &= \{A(\psi), \phi(\psi)\}_\psi \\ &= \{A_\theta(\omega_0), \phi(\omega_0)\}_{\omega_0}, \end{aligned} \quad (29)$$

where we have used Eq.25 in the 3rd step. In the last step we switched from ψ to ω_0 in evaluating the Poisson Brackets and made use of the fact that ϕ is independent of θ :

$$\phi(\psi(\omega_0; \theta)) = \phi(\omega_0). \quad (30)$$

P7.4 [10 + 4 = 14 points]

A particle of mass m moves in one dimension under a potential $V(x) = kx^{-2}$, where x is the Cartesian coordinate and k a constant.

- (a) Find $x(t)$ using the Poisson bracket form of the equation of motion for the quantity $y = x^2$ given the initial conditions $x(0) = x_0$, $p(0) = 0$.
- (b) Show that the quantity $D = xp - 2Ht$ is a constant of the motion.

S7.4 (a) Using Eq. 28, we can write

$$f(t) = \sum_{n=0}^{\infty} \frac{1}{n!} (\mathcal{H}^n f)_0 t^n = f(0) + (\mathcal{H}f)_0 t + \frac{1}{2!} (\mathcal{H}^2 f)_0 t^2 + \frac{1}{3!} (\mathcal{H}^3 f)_0 t^3 + \dots, \quad (31)$$

where the operator \mathcal{H} is defined as the Poisson bracket with the Hamiltonian:

$$\mathcal{H}f \equiv \{f, H\} \quad (32)$$

for any function $f(q, p, t)$. The subscript “0” indicates that the PB’s are evaluated at $t = 0$.

Now,

$$H = \frac{p^2}{2m} + \frac{k}{x^2}. \quad (33)$$

So, for $y = x^2$ we have for the second term in the sum (since $\{f(x), g(x)\} = 0$),

$$\mathcal{H}y = \{x^2, H\} = \frac{1}{2m}\{x^2, p^2\} = \frac{1}{2m} \left(\frac{\partial}{\partial x} x^2 \right) \left(\frac{\partial}{\partial p} p^2 \right) = \frac{2xp}{m}. \quad (34)$$

The next term is

$$\begin{aligned} \mathcal{H}^2 y &= \mathcal{H}(\mathcal{H}x^2) = \mathcal{H} \left(\frac{2xp}{m} \right) \\ &= \frac{2}{m} \{xp, H\} \\ &= \frac{2}{m} (x\{p, H\} + p\{x, H\}) \\ &= \frac{2}{m} \left(x \left\{ p, \frac{k}{x^2} \right\} + p \left\{ x, \frac{p^2}{2m} \right\} \right) \\ &= \frac{2}{m} \left(-x \frac{\partial}{\partial x} \left(\frac{k}{x^2} \right) + \frac{p}{2m} \left(\frac{\partial}{\partial p} (p^2) \right) \right) \\ &= \frac{2}{m} \left(\frac{2k}{x^2} + \frac{p^2}{m} \right) \\ &= \frac{4}{m} H. \end{aligned} \quad (35)$$

For $n = 3$,

$$\mathcal{H}^3 y = \mathcal{H}(\mathcal{H}^2 y) = \frac{4}{m} \mathcal{H}H = \frac{4}{m} \{H, H\} = 0. \quad (36)$$

Hence, all higher terms are zero, and the series terminates at $n = 2$. Thus the solution is a quadratic function in t :

$$\begin{aligned} x^2(t) &= x_0^2 + \frac{2}{m} x_0 p_0 t + \frac{2}{m} H_0 t^2 \\ &= x_0^2 + \frac{2}{m} x_0 p_0 t + \frac{2}{m} \left(\frac{p_0^2}{2m} + \frac{k}{x_0^2} \right) t^2. \end{aligned} \quad (37)$$

This is an example of how the Poisson brackets can be used to propagate a function in time (or any other parameter, for that matter) from given initial conditions. For $p_0 = 0$,

$$\begin{aligned} x^2(t) &= x_0^2 + \frac{2k}{m x_0^2} t^2, \\ \text{or, } x(t) &= \left(x_0^2 + \frac{2k}{m x_0^2} t^2 \right)^{\frac{1}{2}}. \end{aligned} \quad (38)$$

(b) The rate of change of D with t is given by

$$\frac{dD}{dt} = \{D, H\} + \frac{\partial D}{\partial t}. \quad (39)$$

Now, using Eq. 35,

$$\{D, H\} = \{xp, H\} - 2t\{H, H\} = -2H - 0 = -2H = -\frac{\partial D}{\partial t}, \quad (40)$$

or,

$$\frac{dD}{dt} = \{D, H\} + \frac{\partial D}{\partial t} = 0, \quad (41)$$

Hence, D is a constant of the motion.