

Assignment: HW4 [40 points]

Assigned: 2006/10/25

Due: 2006/11/01

P4.1 [4 + 4 = 8 points]

- (a) Find the moment of inertia tensor I of a uniform cube of side s and mass M whose pivot is at a corner and whose sides are lined up along the axes of an orthonormal coordinate system.
- (b) Find the principal axis system and the moments of inertia.

P4.2 [4 points]

The cube in Problem 1 rotates instantaneously about the edge that is lined up along the x_1 axis. Find the angle between the angular momentum \mathbf{L} and the angular velocity $\vec{\omega}$.

P4.3 [4 points]

Consider the symmetric dumbbell rotating in a “double cone” about its CM as shown in Fig. 4.3: two equal point masses m connected by a massless inextensible link of length 2ℓ . Find the angular momentum of the system and the torque required to maintain the motion.

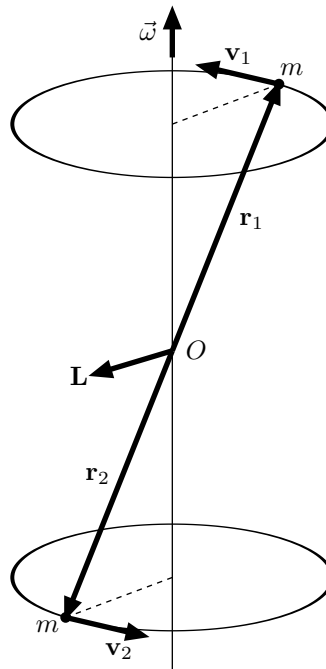


Figure 4.3

P4.4 [8 points]

Find the characteristic frequencies of the coupled circuits in Fig. 4.4.

Comment on the two modes of oscillation (*Hint: only one mode is damped*). Examine how the damped mode depends on the relation between R^2 and $\frac{L}{C}$.

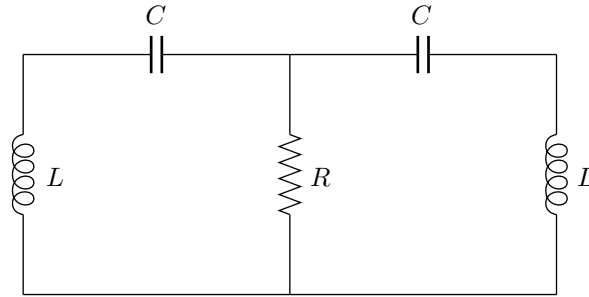


Figure 4.4

P4.5 [10 points]

A mass M moves horizontally along a smooth rail. A pendulum of mass m hangs from M by a massless rod of length ℓ in a uniform vertical gravitational field \mathbf{g} as shown in Fig. 4.5. Ignore all terms of order θ^3 and higher in expansions of trigonometric functions, as well as terms of order $\theta^2\dot{\theta}$ and higher in the Lagrangian. Find the eigenfrequencies and describe the normal modes.

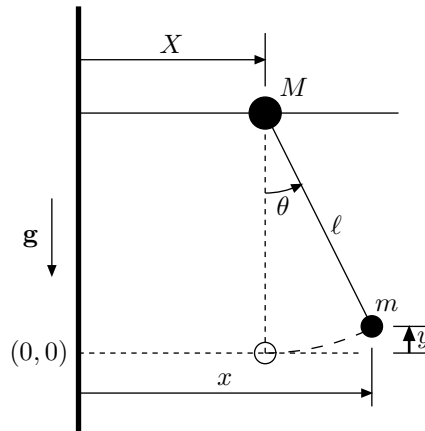


Figure 4.5

P4.6 [6 points]

Three oscillators of equal mass m moving in one dimension are coupled such that the potential energy of the system is given by

$$U = \frac{1}{2} [\kappa_1(x_1^2 + x_3^2) + \kappa_2x_2^2 + \kappa_3(x_1x_2 + x_2x_3)] \quad (1)$$

where

$$\kappa_3 = \sqrt{2\kappa_1\kappa_2}. \quad (2)$$

Find the eigenfrequencies by solving the secular equation. What is the physical interpretation for the zero-frequency mode?